

# HPO-CLD: HP Omnicept - Cognitive Load Dataset

## 1. Introduction

This file describes the data released in the HP Omnicept – Cognitive Load Dataset (HPO-CLD). Please see the accompanying technical report ([HPO-CLD Technical Report](#)) for more details. This dataset contains a subset of the data collected as part of a larger, international research effort to develop a commercial, AI “inference engine” to recognize and assess real-time mental effort (i.e., cognitive load) in virtual reality (VR). To that end, we have developed a scientifically validated solution that reliably predicts cognitive load in the general population (HP Reverb G2 Omnicept Edition) and as part of that effort, we are releasing this dataset for non-commercial use.

Physiological measures such as eye-tracking and cardiovascular data strongly correspond to different cognitive (mental) load levels of individuals and can help in inferring the cognitive load. This dataset was created to support researchers and engineers interested in using physiological data to understand human behavior and cognition.

HPO-CLD contains sensor data collected from VR-HMDs retrofitted with eye-tracking and pulse plethysmography (PPG) sensors while participants were immersed in VR performing tasks of varying difficulty that required different amounts cognitive effort to complete. The data repository contains 100 folders with data corresponding to 100 users. The 100 users were randomly selected from an overall pool of 738 users in the data collection protocol. **[Insert consent info]**.

Data includes: sensor data (Bitalino PPG for cardiac activity, Tobii for eye-tracking and pupillometry), task data (difficulty levels, performance), self-report data (NASA TLX scale of mental demands), and demographic data (e.g., age, education, ethnicity).

## 2. File Ordering and Descriptions

The main unzipped file contains 100 folders corresponding to sensor data of 100 users and a license file. Each folder contains the files as listed below with the highlighted naming conventions:

- Participant\_number-tobii date.csv**
- Participant\_number-bitalino date.csv**
- Participant\_number -testlog date.csv**
- Participant\_number -date-event\_log.csv**
- Participant\_number-Demographics.csv**
- Participant\_number-labels.csv**

- Participant\_number-tobii date.csv**

- Contains the timestamps and raw data from the Tobii eye tracking sensor. The sensor output has 28 columns and brief descriptions of columns are given in appendix (6a).
  - Multiple Tobii files inside a folder should be concatenated together to maintain chronology of the timestamps.
- 2. Participant\_number-bitalino date.csv**
- Contains timestamps and raw data from the Bitalino Photoplethysmography single-channel sensor. Columns are named A1 through A6 with A1 carrying the sensor data along with a separate column for timestamp. Please refer appendix (6b) for more details.
  - Some folders include two Bitalino sensor data – one sensor at the forehead and one sensor at the index finger. E.g. Bitalino-1, Bitalino-2.
  - Multiples files of the same Bitalino type (e.g. Bitalino-1) should be concatenated together to maintain chronology of the timestamps.
- 3. Participant\_number -testlog date.csv**
- Logs of transactions and communications that occurred within the system during the data collection protocol (includes timestamp information).
  - Note: If 'pandas read\_csv method' is used to read this file the error\_bad\_lines parameter should be set to false to ensure proper loading. E.g. pd.read\_csv(path, error\_bad\_lines=False).
- 4. Participant\_number-date-event\_log.csv**
- Tracks the events that occurred throughout the protocol. These include task label, (i.e., low, medium or high cognitive load), participant's self-reported mental load (i.e., TLX scored from 0 - 21), along with timestamp, and other variables (described below).
- 5. Participant\_number-Demographics.csv**
- Includes time and date of test session, participant's age, ethnicity, ancestry information, and other variables (described below).
- 6. Participant\_number-labels.csv**
- These data were used as "ground truth" in our modeling (i.e., the labels our models predicted). This file contains the participant ID\*, time start, time end, task difficulty (for classification), and self-reported TLX information (for regression). Please refer to appendix (6c) for more details.

### 3. Labeling Information

- The raw sensor data corresponding to different states of cognitive load can be aligned with the help of **Participant\_number-labels.csv** file inside every folder.

- Each task is marked by a time\_start and time\_end pair that can be matched with the time stamps of raw sensor data to select data between the time interval specified.

\*Note: The original Participant IDs have been replaced with randomly generated HP-CLD IDs as an added level of security for research participants.

## 4. Experiment Setting and Procedure

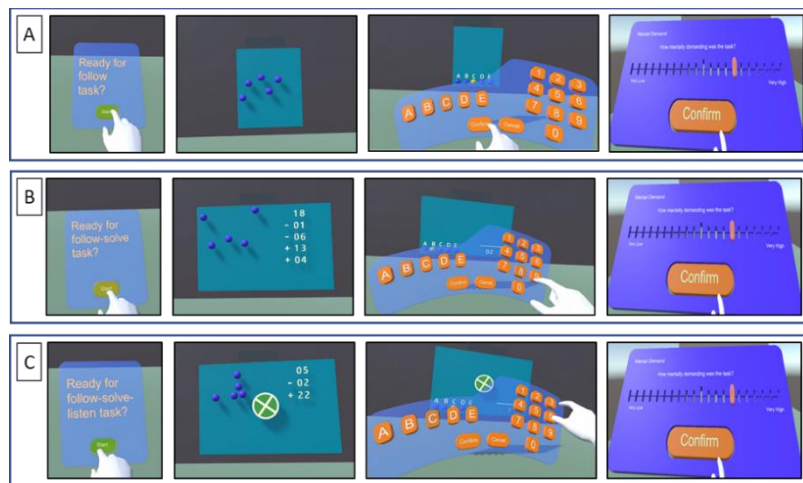


Figure 1. Experiments inducing varied levels of Cognitive Load

Figure 1. represents an Example stimulus from the cognitive load task. On a given trial, participants complete tasks designed to induce different levels of mental effort (low, medium, and high). **Box A** is an overview of a low mental effort trial. In a low trial, five dots move in a random, diverging pattern around the screen. Participants' task is to track a single dot and, when the dots stop moving, indicate which of dots they were tracking. **Box B** is an example of a medium mental effort trial in which participants complete the dot tracking task and a mental math task where numbers and operators appear at random intervals and they are instructed to do the math in their heads. When the dots stop moving and the numbers stop appearing on the screen, participants report which dot they were tracking and their answer to the mental math problem. **Box C** is an example of a high mental effort trial in which participants complete the dot tracking, mental math, and a third, vigilance task, in which they monitor a spinning wheel that changes directions. When they hear a beep, the wheel stops spinning, and they report which direction the wheel was spinning (while simultaneously tracking the dots and doing the math problem). In all three conditions, at the end of each trial, participants then self-report how mentally demanding they found the task on a continuous rating scale from very low to very high

(TLX score). Data from the two sensors were recorded simultaneously as the participant engaged in the described experiment.

## 5. Appendix

- a. The file with 'tobii' contains data from the tobi eye-tracking sensor. The raw data columns and brief descriptions are given below. For more information, please refer <http://developer.tobiipro.com/python/python-sdk-reference-guide.html>.

| Column  | Description  |
|---|--|
| t   | System aligned timestamp when the data point was recorded.               |
| device_time_stamp                               | Isolated timestamp of the sensor.  |
| right_pupil_validity                            | The validity of the right pupil data.<br>1 if valid. 0 if invalid.       |
| left_pupil_validity                             | The validity of the left pupil data.<br>1 if valid. 0 if invalid.        |
| right_gaze_direction_validity                   | The validity of the right gaze direction data. 1 if valid. 0 if invalid. |
| left_gaze_direction_validity                    | The validity of the left gaze direction data. 1 if valid. 0 if invalid.  |
| right_pupil_position_validity                   | The validity of the right pupil position data. 1 if valid. 0 if invalid. |
| left_pupil_position_validity                    | The validity of the left pupil position data. 1 if valid. 0 if invalid.  |
| right_gaze_origin_validity                      | The validity of the right gaze origin data.<br>1 if valid. 0 if invalid. |
| left_gaze_origin_validity                       | The validity of the left gaze origin data.<br>1 if valid. 0 if invalid.  |
| right_pupil_diameter                            | The diameter of the right pupil in millimeters.                          |
| left_pupil_diameter                             | The diameter of the left pupil in millimeters.                           |
| right_gaze_origin_position_in_hmd_coordinates_x | The x coordinate that describes the right gaze origin in mm.             |
| right_gaze_origin_position_in_hmd_coordinates_y | The y coordinate that describes the right gaze origin in mm.             |
| right_gaze_origin_position_in_hmd_coordinates_z | The z coordinate that describes the right gaze origin in mm.             |
| left_gaze_origin_position_in_hmd_coordinates_x  | The x coordinate that describes the left gaze origin in mm.              |
| left_gaze_origin_position_in_hmd_coordinates_y  | The y coordinate that describes the left gaze origin in mm.              |

|  |  |
|--|--|
| left_gaze_origin_position_in_hmd_coordinates_z | The z coordinate that describes the left gaze origin in mm.  |
| right_gaze_direction_unit_vector_x             | The x component of unit vector that describes the right gaze direction in 3D.                                      |
| right_gaze_direction_unit_vector_y             | The y component of unit vector that describes the right gaze direction in 3D.                                      |
| right_gaze_direction_unit_vector_z             | The z component of unit vector that describes the right gaze direction in 3D.                                      |
| left_gaze_direction_unit_vector_x              | The x component of unit vector that describes the left gaze direction in 3D.                                       |
| left_gaze_direction_unit_vector_y              | The y component of unit vector that describes the left gaze direction in 3D.                                       |
| left_gaze_direction_unit_vector_z              | The z component of unit vector that describes the left gaze direction in 3D.                                       |
| right_pupil_position_in_tracking_area_x        | The x component of normalized 2D coordinates that describes the right pupil's position in the HMD's tracking area. |
| right_pupil_position_in_tracking_area_y        | The y component of normalized 2D coordinates that describes the right pupil's position in the HMD's tracking area. |
| left_pupil_position_in_tracking_area_x         | The x component of normalized 2D coordinates that describes the left pupil's position in the HMD's tracking area.  |
| left_pupil_position_in_tracking_area_y         | The y component of normalized 2D coordinates that describes the left pupil's position in the HMD's tracking area.  |

- b. The file with 'bitalino' contains data from the Bitalino PPG sensor. The raw data columns and brief descriptions are given below.

| Column | Descriptions  |
|--------|---|
| t      | System aligned timestamp when the data point was recorded |
| A1     | Data channel representing raw pulse information           |
| A2     | Unused channel, noise                                     |
| A3     | Unused channel, noise                                     |
| A4     | Unused channel, noise                                     |
| A5     | Unused channel, noise                                     |
| A6     | Unused channel, noise                                     |

- c. The file with 'labels' contains ground truth information and time intervals of tasks. Brief descriptions are given below:

| Column               | Description  |
|----------------------|--|
| Participant ID       | ID of the participant during data collection   |
| time_start           | Time boundary marking the beginning of task  |
| time_end             | Time boundary marking the end of task  |
| task_difficulty      | Difficulty of the task inducing cognitive load in accordance                               |
| TLX_score            | Participant's self-reported difficulty score on a scale of 0 - 21                          |
| CRR                  | Correct Response Rate – agreement of CLX rating with task difficulty                       |
| reweighted_TLX_score | Combined individual TLX rating with population wide TLX task averages using a weighted sum |

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